

Universitas Negeri Surabaya Faculty of Mathematics and Natural Sciences Physics Education Undergraduate Study Program

Document Code

SEMESTER LEARNING PLAN

Courses		CODE	Course Family	C	Credit Weight			SEMESTER	Compilation Date			
Robotics Physics		8420302266		т	Г=2	P=0	ECTS=3.18	5	July 18, 2024			
AUTHORIZATION		SP Developer		Course Cluster Coordinator			r	Study Program Coordinator				
								Mita Anggaryani, M.Pd., Ph.D.				
Learning model	Project Based Learning											
Program Learning Outcomes (PLO)	PLO study program that is charged to the course											
	Program Objectives (PO)											
	PLO-PO Matrix											
	P.0											
	PO Matrix at the end of each learning stage (Sub-PO)											
		P.O 1 2 3 4	4 5 6	6 7	8	Wee 9		2 13 14	15 16			
Short Course Description	Robotics is a course that studies the concepts, functions and applications of robots. Students will learn about robot components, including sensors, actuators, mechanical design and algorithms. Students will be given assignments and need to design and build various projects (moving robots and arm manipulator robots) using these components. Students will work independently or in small groups on the topics: 1. Introduction to Robotics (concepts, functions and implementation) in various fields 2. Sensors and actuators used for robots 3. Mechanical design of robots 4. Inverse kinematics for controlling robots 5. Design and control of mobile robots (wheeled and legged) Design and control of arm manipulator robots											
References	Main :								-			
	 [1]. M. Quigley, B. Gerkey and W.D Smart, Programing Robots with ROS, O'Reilly. 2015. 2. C.D.Simpson, ROS Robot Pragramming, Robotis, 2017. 3. S. Thrun. M. Burgard, D.Fox,Probabilistic Robotics, MIT Pres. 2006. 2]. Mihelj, M. et.al. 2019. Robotics. 2nd Edition. Switzerland: Springer, pp. 1-247. ISBN 978-3- 319-72911-4. [3]. Margolis, M. 2012. Make An Arduino Controlled Robot. United State of America: O'Reilly Media Inc., pp. 1-235. ISBN: 978-1-449-34437-5. [4]. Cook, D. 2015. Robot Building for Beginners. 3rd Edition. New York: Springer, pp.1- 449. ISBN-13: 978-1-4842-1359-9. [5]. Siciliano, B. and Khatib, O. Handbook of Robotics. Berlin: Springer-Verlag, pp. 1-1559. e-ISBN: 978-3-540-30301-5.Levin, 											
	Supporters:											
		1										
Supporting lecturer	Drs. Imam Su Dzulkiflih, S.S											

Week-	Final abilities of each learning stage (Sub-PO)	E	valuation	Le Stu	Help Learning, arning methods, dent Assignments, Estimated time]	Learning materials [References]	Assessment Weight (%)
		Indicator	Criteria & Form	Offline (offline)	Online (<i>online</i>)		
(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)
1							0%
2							0%
3							0%
4							0%
5							0%
6							0%
7							0%
8							0%
9							0%
10							0%
11							0%
12							0%
13							0%
14							0%
15							0%
16							0%

 Evaluation Percentage Recap: Project Based Learning

 No
 Evaluation

 Percentage

 0%

Notes

- 1. Learning Outcomes of Study Program Graduates (PLO Study Program) are the abilities possessed by each Study Program graduate which are the internalization of attitudes, mastery of knowledge and skills according to the level of their study program obtained through the learning process.
- The PLO imposed on courses are several learning outcomes of study program graduates (CPL-Study Program) which are used for the formation/development of a course consisting of aspects of attitude, general skills, special skills and knowledge.
- 3. **Program Objectives (PO)** are abilities that are specifically described from the PLO assigned to a course, and are specific to the study material or learning materials for that course.
- 4. **Subject Sub-PO (Sub-PO)** is a capability that is specifically described from the PO that can be measured or observed and is the final ability that is planned at each learning stage, and is specific to the learning material of the course.
- 5. **Indicators for assessing** ability in the process and student learning outcomes are specific and measurable statements that identify the ability or performance of student learning outcomes accompanied by evidence.
- 6. Assessment Criteria are benchmarks used as a measure or measure of learning achievement in assessments based on predetermined indicators. Assessment criteria are guidelines for assessors so that assessments are consistent and unbiased. Criteria can be quantitative or qualitative.

- 7. Forms of assessment: test and non-test.
- 8. Forms of learning: Lecture, Response, Tutorial, Seminar or equivalent, Practicum, Studio Practice, Workshop
- Practice, Field Practice, Research, Community Service and/or other equivalent forms of learning.
 Learning Methods: Small Group Discussion, Role-Play & Simulation, Discovery Learning, Self-Directed Learning, Cooperative Learning, Collaborative Learning, Contextual Learning, Project Based Learning, and other equivalent methods.
- 10. Learning materials are details or descriptions of study materials which can be presented in the form of several main points and sub-topics.
- 11. The assessment weight is the percentage of assessment of each sub-PO achievement whose size is proportional to the level of difficulty of achieving that sub-PO, and the total is 100%. 12. TM=Face to face, PT=Structured assignments, BM=Independent study.