



Universitas Negeri Surabaya
Faculty of Engineering,
Mechanical Engineering Undergraduate Study Program

Document Code

SEMESTER LEARNING PLAN

Courses	CODE	Course Family	Credit Weight	SEMESTER	Compilation Date																																
Robotics	2120102080		T=2 P=0 ECTS=3.18	7	July 18, 2024																																
AUTHORIZATION	SP Developer		Course Cluster Coordinator	Study Program Coordinator																																	
	Ir. Priyo Heru Adiwibowo, S.T., M.T.																																	
Learning model	Case Studies																																				
Program Learning Outcomes (PLO)	PLO study program that is charged to the course																																				
	Program Objectives (PO)																																				
	PLO-PO Matrix																																				
		<table border="1" style="margin: auto;"> <tr><td style="width: 30px;">P.O</td></tr> </table>				P.O																															
P.O																																					
Short Course Description	Study of robot classification, components forming robots, application of frames on robot links, analysis of kinematics and inverse kinematics of manipulators, analysis of speed and static forces on manipulators, analysis of robot dynamics, design of manipulator mechanisms, and programming of robot manipulators.																																				
	<table border="1" style="width: 100%; text-align: center;"> <tr> <td rowspan="2" style="width: 30px;">P.O</td> <td colspan="16">Week</td> </tr> <tr> <td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td><td>16</td> </tr> </table>					P.O	Week																1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
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References	Main :																																				
	<ol style="list-style-type: none"> 1. Koren, Yoram 1989. Robotics for Engineers John Wiley & Sons, New York. Craig. 2. John J., 1989. Introduction to Robotic; mechanic and control. Addison-Wesley Publishing Company: New York. 3. Poole, Harry H., 1989. Fundamentals of Robotic Engineering. Programming and Reinhold: New York. 																																				
	Supporters:																																				
Supporting lecturer																																					
Week-	Final abilities of each learning stage (Sub-PO)	Evaluation		Help Learning, Learning methods, Student Assignments, [Estimated time]		Learning materials [References]	Assessment Weight (%)																														
		Indicator	Criteria & Form	Offline (offline)	Online (online)																																
(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)																														

1	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
2	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
3	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
4	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%

5	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
6	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
7	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
8	UTS	UTS	Criteria: Compliance with the answer key gets a score of 100	UTS 2 X 50			0%
9	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%

10	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
11	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
12	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
13	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%

14	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
15	Understanding robot classification	Explain the definition of a robot. Identify the various types of robots	Criteria: Compliance with the answer key gets a score of 100	Approach: Contextual based learning Method: Lecture, discussion, question and answer Model: MPL, MPK, MPBM Strategy: Guided practice and assignments 2 X 50			0%
16							0%

Evaluation Percentage Recap: Case Study

No	Evaluation	Percentage
		0%

Notes

- Learning Outcomes of Study Program Graduates (PLO - Study Program)** are the abilities possessed by each Study Program graduate which are the internalization of attitudes, mastery of knowledge and skills according to the level of their study program obtained through the learning process.
- The PLO imposed on courses** are several learning outcomes of study program graduates (CPL-Study Program) which are used for the formation/development of a course consisting of aspects of attitude, general skills, special skills and knowledge.
- Program Objectives (PO)** are abilities that are specifically described from the PLO assigned to a course, and are specific to the study material or learning materials for that course.
- Subject Sub-PO (Sub-PO)** is a capability that is specifically described from the PO that can be measured or observed and is the final ability that is planned at each learning stage, and is specific to the learning material of the course.
- Indicators for assessing** ability in the process and student learning outcomes are specific and measurable statements that identify the ability or performance of student learning outcomes accompanied by evidence.
- Assessment Criteria** are benchmarks used as a measure or measure of learning achievement in assessments based on predetermined indicators. Assessment criteria are guidelines for assessors so that assessments are consistent and unbiased. Criteria can be quantitative or qualitative.
- Forms of assessment:** test and non-test.
- Forms of learning:** Lecture, Response, Tutorial, Seminar or equivalent, Practicum, Studio Practice, Workshop Practice, Field Practice, Research, Community Service and/or other equivalent forms of learning.
- Learning Methods:** Small Group Discussion, Role-Play & Simulation, Discovery Learning, Self-Directed Learning, Cooperative Learning, Collaborative Learning, Contextual Learning, Project Based Learning, and other equivalent methods.
- Learning materials** are details or descriptions of study materials which can be presented in the form of several main points and sub-topics.
- The assessment weight** is the percentage of assessment of each sub-PO achievement whose size is proportional to the level of difficulty of achieving that sub-PO, and the total is 100%.
- TM=Face to face, PT=Structured assignments, BM=Independent study.

