



**Universitas Negeri Surabaya  
Faculty of Engineering,  
Mechanical Engineering Undergraduate Study Program**

Document Code

### SEMESTER LEARNING PLAN

<b>Courses</b>	<b>CODE</b>	<b>Course Family</b>	<b>Credit Weight</b>			<b>SEMESTER</b>	<b>Compilation Date</b>																																
Kinematics Dynamics 1	2120102115	Compulsory Study Program Subjects	T=2	P=0	ECTS=3.18	2	September 6, 2023																																
<b>AUTHORIZATION</b>		<b>SP Developer</b>	<b>Course Cluster Coordinator</b>			<b>Study Program Coordinator</b>																																	
		Ika Nurjannah, S.Pd., M.T. ; Diastian Vinaya Wijanarko, S.T., M.T.; Ir. Priyo Heru Adiwibowo, S.T., M.T.	Diastian Vinaya Wijanarko, S.T., M.T.			Ir. Priyo Heru Adiwibowo, S.T., M.T.																																	
<b>Learning model</b>	<b>Case Studies</b>																																						
<b>Program Learning Outcomes (PLO)</b>	<b>PLO study program that is charged to the course</b>																																						
	<b>PLO-5</b>	Work independently and in groups																																					
	<b>PLO-6</b>	Experimentation and data analysis																																					
	<b>PLO-11</b>	Design and development of solutions that take into account the environment and sustainability																																					
	<b>PLO-14</b>	Science and engineering knowledge																																					
	<b>Program Objectives (PO)</b>																																						
	<b>PLO-PO Matrix</b>																																						
		<table border="1" style="margin: auto;"> <tr> <td style="width: 15%;">P.O</td> <td style="width: 15%;">PLO-5</td> <td style="width: 15%;">PLO-6</td> <td style="width: 15%;">PLO-11</td> <td style="width: 15%;">PLO-14</td> </tr> </table>						P.O	PLO-5	PLO-6	PLO-11	PLO-14																											
	P.O	PLO-5	PLO-6	PLO-11	PLO-14																																		
	<b>PO Matrix at the end of each learning stage (Sub-PO)</b>																																						
	<table border="1" style="margin: auto;"> <tr> <td rowspan="2" style="width: 10%;">P.O</td> <td colspan="16" style="text-align: center;">Week</td> </tr> <tr> <td style="width: 5%;">1</td> <td style="width: 5%;">2</td> <td style="width: 5%;">3</td> <td style="width: 5%;">4</td> <td style="width: 5%;">5</td> <td style="width: 5%;">6</td> <td style="width: 5%;">7</td> <td style="width: 5%;">8</td> <td style="width: 5%;">9</td> <td style="width: 5%;">10</td> <td style="width: 5%;">11</td> <td style="width: 5%;">12</td> <td style="width: 5%;">13</td> <td style="width: 5%;">14</td> <td style="width: 5%;">15</td> <td style="width: 5%;">16</td> </tr> </table>						P.O	Week																1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
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	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16																							
<b>Short Course Description</b>	Understanding, mastery and analysis of the material of kinematics of particles & rigid bodies in absolute & relative motion, position, speed and acceleration of objects as well as kinematics in a slider-crank & four-bar linkage mechanism using graphical methods.																																						
<b>References</b>	<b>Main :</b>																																						
	<ol style="list-style-type: none"> <li>1. R. C. Hibbeler. 2010. Engineering Mechanics: Dynamics, 12th Edition. Prentice Hall Inc.</li> <li>2. David H. Myszka. 2012. Machines and Mechanism Applied Kinematic Analysis, 4th Edition. Prentice Hall Inc.</li> <li>3. Priyo Heru Adiwibowo. 2013. Kinematika dan Dinamika, Bagian 1 Kinematika. Unesa Uiversity Press.</li> <li>4. Martin, George H. 1982. Kinematics and Dynamics of Mechanics, 2nd Edition. McGraw Hill.</li> <li>5. Ferdinand P. Beer, E. Russell Johnston Jr. 2010. Vector Mechanics for Engineers, Static and Dynamics, 9th Edition. McGraw Hill.</li> <li>6. J. L. Meriam, L. G. Kraige. 2012. Engineering Mechanics, 7nd Edition. John Wiley and Sons Inc.</li> </ol>																																						
	<b>Supporters:</b>																																						
<b>Supporting lecturer</b>	Ir. Priyo Heru Adiwibowo, S.T., M.T. Diastian Vinaya Wijanarko, S.T., M.T. Ahmad Saepuddin, S.T., M.Sc. Ika Nurjannah, S.Pd., M.T.																																						

Week-	Final abilities of each learning stage (Sub-PO)	Evaluation		Help Learning, Learning methods, Student Assignments, [ Estimated time]		Learning materials [ References ]	Assessment Weight (%)
		Indicator	Criteria & Form	Offline ( offline )	Online ( online )		
(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)
1	Students are able to understand and analyze the basic concepts of Kinematics and Dynamics and are able to use Physical Quantities, Symbols and Units	1.Able to explain Kinematic analysis of particle dynamics, rigid bodies and mechanisms 2.Able to use physical quantities, symbols and units	<b>Criteria:</b> Compliance with the answer key	Introductory lecture and brainstorming, Lecture, discussion, questions and answers 2 X 50			0%
2	Students are able to determine the Degrees of Freedom (DoF) in mechanisms and are able to use vectors in dynamic kinematics	1.Able to draw kinematic diagrams 2.Able to determine degrees of freedom 3.Skilled in using vectors	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions, questions and answers, exercises and assignments 2 X 50			0%
3	Students are able to understand and analyze particles in straight, rectangular, curved and projectile motion.	1.Able to distinguish & analyze the movement of a particle. 2.Able and skilled at solving kinematics problems	<b>Criteria:</b> Compliance with the answer key	Discussion, questions and answers, exercises and assignments 2 X 50			0%
4	Students are able to understand and analyze the relative motion of two particles	1.Able to analyze the relative motion of two particles 2.Skilled in solving problems of relative motion of two particles	<b>Criteria:</b> Compliance with the answer key	Discussion and questions and answers 2 X 50			0%
5	Students are able to understand the motion of rigid bodies in kinematics and are able to analyze translational and rotational motion	1.Able to analyze the kinematics of rigid bodies 2.Skilled in solving kinematics problems of translational and rotational rigid bodies	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%
6	Students are able to understand movement in the absolute plane and speed in the relative motion of rigid bodies	Able to analyze and be skilled at solving speed problems in the relative motion of rigid objects	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%

7	Students are able to understand acceleration in the relative motion of rigid bodies and are able to analyze speed & acceleration in the relative motion of rigid bodies	1.Able to analyze acceleration problems in the relative motion of rigid bodies 2.Skilled in using the relative motion of rigid bodies at speed and acceleration	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%
8	UTS	UTS	<b>Criteria:</b> Compliance with the answer key	UTS 2 X 50			0%
9	Students are able to understand the simple mechanism of slider-crank and four-bar linkage	1.Able to differentiate slider-crank and four-bar linkage mechanisms 2.Skilled in drawing kinematic diagrams	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%
10	Students are able to determine the position of all links in a mechanism	Able to calculate and draw changes in the position of each link in the slider-crank mechanism and four-bar linkage	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions, questions and answers 2 X 50			0%
11	Students are able to relate linear speed and angular speed and are able to use the relative speed method in the slider-crank mechanism	Able to calculate and draw the speed of each point on the slider-crank mechanism	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%
12	Students are able to relate linear speed and angular speed and are able to use the relative speed method in the four-bar linkage mechanism	Able to calculate and draw the speed of each point on the four-bar linkage mechanism	<b>Criteria:</b> Compliance with the answer key	Discussion and questions and answers 2 X 50			0%
13	Students are able to use the relative acceleration method on the slider-crank mechanism	Able to calculate and draw acceleration diagrams for each point on the slider-crank mechanism	<b>Criteria:</b> Compliance with the answer key	Lectures, discussions and questions and answers 2 X 50			0%
14	Students are able to use the relative acceleration method in the four-bar linkage mechanism	Able to calculate and draw acceleration diagrams for each point on the four-bar linkage mechanism	<b>Criteria:</b> Compliance with the answer key	Discussion and questions and answers 2 X 50			0%
15	Students are able to understand speed and acceleration in the Coriolis mechanism	Able to draw velocity and acceleration diagrams of Coriolis bodies	<b>Criteria:</b> Compliance with the answer key	Caramah, discussion and questions and answers 2 X 50			0%
16	UAS	UAS	<b>Criteria:</b> Compliance with the answer key	UAS 2 X 50			0%

No	Evaluation	Percentage
		0%

#### Notes

1. **Learning Outcomes of Study Program Graduates (PLO - Study Program)** are the abilities possessed by each Study Program graduate which are the internalization of attitudes, mastery of knowledge and skills according to the level of their study program obtained through the learning process.
2. **The PLO imposed on courses** are several learning outcomes of study program graduates (CPL-Study Program) which are used for the formation/development of a course consisting of aspects of attitude, general skills, special skills and knowledge.
3. **Program Objectives (PO)** are abilities that are specifically described from the PLO assigned to a course, and are specific to the study material or learning materials for that course.
4. **Subject Sub-PO (Sub-PO)** is a capability that is specifically described from the PO that can be measured or observed and is the final ability that is planned at each learning stage, and is specific to the learning material of the course.
5. **Indicators for assessing** ability in the process and student learning outcomes are specific and measurable statements that identify the ability or performance of student learning outcomes accompanied by evidence.
6. **Assessment Criteria** are benchmarks used as a measure or measure of learning achievement in assessments based on predetermined indicators. Assessment criteria are guidelines for assessors so that assessments are consistent and unbiased. Criteria can be quantitative or qualitative.
7. **Forms of assessment:** test and non-test.
8. **Forms of learning:** Lecture, Response, Tutorial, Seminar or equivalent, Practicum, Studio Practice, Workshop Practice, Field Practice, Research, Community Service and/or other equivalent forms of learning.
9. **Learning Methods:** Small Group Discussion, Role-Play & Simulation, Discovery Learning, Self-Directed Learning, Cooperative Learning, Collaborative Learning, Contextual Learning, Project Based Learning, and other equivalent methods.
10. **Learning materials** are details or descriptions of study materials which can be presented in the form of several main points and sub-topics.
11. **The assessment weight** is the percentage of assessment of each sub-PO achievement whose size is proportional to the level of difficulty of achieving that sub-PO, and the total is 100%.
12. TM=Face to face, PT=Structured assignments, BM=Independent study.