

## Universitas Negeri Surabaya Faculty of Mathematics and Natural Sciences Data Science Undergraduate Study Program

Document Code

| SEMESTER LEARNING PLAN         |   |                                |                  |      |                               |        |                                      |                |                  |  |
|--------------------------------|---|--------------------------------|------------------|------|-------------------------------|--------|--------------------------------------|----------------|------------------|--|
| Courses                        |   | CODE                           | Course<br>Family |      | Cred                          | lit We | ight                                 | SEMESTER       | Compilation Date |  |
| Robotics                       |   | 4920203045                     |                  |      | T=3                           | P=0    | ECTS=4.77                            | 6              | July 18, 2024    |  |
| AUTHORIZATION                  |   | SP Developer                   | P Developer      |      | Course Cluster<br>Coordinator |        | Study Program<br>Coordinator         |                |                  |  |
|                                |   |                                |                  |      |                               |        | Yuliani Puji Astuti, S.Si.,<br>M.Si. |                |                  |  |
| Learning<br>model              | Project Base  | ct Based Learning              |                  |      |                               |        |                                      |                |                  |  |
| Program<br>Learning            | PLO study program that is charged to the course   |                                |                  |      |                               |        |                                      |                |                  |  |
| Outcomes                       | Program Objectives (PO)   |                                |                  |      |                               |        |                                      |                |                  |  |
| (PLO)                          | PLO-PO Matrix   |                                |                  |      |                               |        |                                      |                |                  |  |
|                                | P.O   |                                |                  |      |                               |        |                                      |                |                  |  |
|                                | PO Matrix at the end of each learning stage (Sub-PO)  |                                |                  |      |                               |        |                                      |                |                  |  |
|                                |   | P.O 1 2 3 4                    | 5 6              | 7    | 8                             | Wee    | ek<br>10 11 1:                       | 2 13 14        | 15 16            |  |
| Short<br>Course<br>Description | In this lecture,<br>design are dis  | the basics of robotics cussed. | s, robotic       | mode | eling a                       | and si | mulation, exa                        | mples of robot | ics and robotic  |  |
| References                     | Main :  |                                |                  |      |                               |        |                                      |                |                  |  |
|                                | <ol> <li>Groover, et.al., [1986], "Industrial Robotics", McGraw Hill Book Coy., New York</li> <li>Endra Pitowarno.(2006). Robotika, Desain, Kontrol dan Kecerdasan Buatan, Andi Yojakarta.</li> <li>K.S. Fu, R.C. Gonzalis, G.S.G. Lee. (1987). Robotics, Control, Sensing, Vision and Intelligence, Mc. Graw Hill.</li> <li>William Karl. (2003). Amphibionics, Build Your Own Biologically Inspired Robot. Mc-Graww Hill.</li> <li>Shirclif, David R. (2002). Build a Remote Controlled Robot., Mc-Graw Hill.</li> <li>Edward, Lewin A.R.W. (2005). Open Source Robotic and Process Control Cook Book, Elsevier Inc.</li> <li>Lovine John. (2002). Robots, Androids, and Animatrons. Mc. Graw Hill</li> </ol> Supporters: |                                |                  |      |                               |        |                                      |                |                  |  |
|                                |   |                                |                  |      |                               |        |                                      |                |                  |  |
| Supporting lecturer            |   |                                |                  |      |                               |        |                                      |                |                  |  |

| Week- | Final<br>abilities of<br>each<br>learning<br>stage<br>(Sub-PO) | Evaluation |                 |                              | Help Learning,<br>earning methods,<br>dent Assignments,<br>Estimated time] | Learning<br>materials<br>[<br>References | Assessment |
|-------|--|------------|-----------------|------------------------------|--|--|------------|
|       |  | Indicator  | Criteria & Form | Offline<br>(<br>offline<br>) | Online ( <i>online</i> )   | References ]                             | Weight (%) |
| (1)   | (2)  | (3)        | (4)             | (5)                          | (6)  | (7)                                      | (8)        |
| 1     |  |            |                 |                              |  |  | 0%         |
| 2     |  |            |                 |                              |  |  | 0%         |
| 3     |  |            |                 |                              |  |  | 0%         |
| 4     |  |            |                 |                              |  |  | 0%         |
| 5     |  |            |                 |                              |  |  | 0%         |
| 6     |  |            |                 |                              |  |  | 0%         |
| 7     |  |            |                 |                              |  |  | 0%         |
| 8     |  |            |                 |                              |  |  | 0%         |
| 9     |  |            |                 |                              |  |  | 0%         |
| 10    |  |            |                 |                              |  |  | 0%         |
| 11    |  |            |                 |                              |  |  | 0%         |
| 12    |  |            |                 |                              |  |  | 0%         |
| 13    |  |            |                 |                              |  |  | 0%         |
| 14    |  |            |                 |                              |  |  | 0%         |
| 15    |  |            |                 |                              |  |  | 0%         |
| 16    |  |            |                 |                              |  |  | 0%         |

**Evaluation Percentage Recap: Project Based Learning** 

|    |            | orrange races | <br> | ; |
|----|------------|---------------|------|---|
| No | Evaluation | Percentage    |      |   |
|    |            | 006           |      |   |

## Notes

- Learning Outcomes of Study Program Graduates (PLO Study Program) are the abilities possessed by each Study Program graduate which are the internalization of attitudes, mastery of knowledge and skills according to the level of their study program obtained through the learning process.
- 2. **The PLO imposed on courses** are several learning outcomes of study program graduates (CPL-Study Program) which are used for the formation/development of a course consisting of aspects of attitude, general skills, special skills and knowledge.
- 3. **Program Objectives (PO)** are abilities that are specifically described from the PLO assigned to a course, and are specific to the study material or learning materials for that course.
- 4. **Subject Sub-PO (Sub-PO)** is a capability that is specifically described from the PO that can be measured or observed and is the final ability that is planned at each learning stage, and is specific to the learning material of the course.
- Indicators for assessing ability in the process and student learning outcomes are specific and measurable statements that identify the ability or performance of student learning outcomes accompanied by evidence.
- 6. Assessment Criteria are benchmarks used as a measure or measure of learning achievement in assessments based on predetermined indicators. Assessment criteria are guidelines for assessors so that assessments are consistent and unbiased. Criteria can be quantitative or qualitative.
- 7. Forms of assessment: test and non-test.

- 8. **Forms of learning:** Lecture, Response, Tutorial, Seminar or equivalent, Practicum, Studio Practice, Workshop Practice, Field Practice, Research, Community Service and/or other equivalent forms of learning.
- Learning Methods: Small Group Discussion, Role-Play & Simulation, Discovery Learning, Self-Directed Learning, Cooperative Learning, Collaborative Learning, Contextual Learning, Project Based Learning, and other equivalent methods.
- 10. Learning materials are details or descriptions of study materials which can be presented in the form of several main points and sub-topics.
- 11. The assessment weight is the percentage of assessment of each sub-PO achievement whose size is proportional to the level of difficulty of achieving that sub-PO, and the total is 100%.
- 12. TM=Face to face, PT=Structured assignments, BM=Independent study.